

In this lecture, we introduce the *complementary slackness* conditions and use them to obtain a primal-dual method for solving linear programming.

## 1 Complementary Slackness

As we have seen before, using strong duality, we know that the optimum value for the following two linear programming are equal, i.e.  $u = w$ , if they are both feasible.

$$u = \max\{c^T x : Ax \leq b, x \geq 0\} \quad (P)$$

$$w = \min\{b^T y : A^T y \geq c, y \geq 0\} \quad (D)$$

Using the above result, we can check the optimality of a primal and/or a dual solution.

**Theorem 1.** *Suppose  $x$  and  $y$  are feasible solutions to  $(P)$  and  $(D)$ . Then  $x$  and  $y$  are optimal if and only if the following conditions are satisfied:*

$$\forall i (b_i - \sum_j a_{ij}x_j)y_i = 0;$$

$$\forall j (\sum_i a_{ij}y_i - c_j)x_j = 0.$$

*Proof.* First, we note that since  $x$  and  $y$  are feasible  $(b_i - \sum_j a_{ij}x_j)y_i \geq 0$  and  $(\sum_i a_{ij}y_i - c_j)x_j \geq 0$ . By summing over  $i$  and  $j$ , we have:

$$\sum_i (b_i - \sum_j a_{ij}x_j)y_i \geq 0 \quad (1)$$

$$\sum_j (\sum_i a_{ij}y_i - c_j)x_j \geq 0 \quad (2)$$

By adding 1 and 2 and using the strong duality theorem

$$\sum_i b_i y_i - \sum_{i,j} a_{ij} x_j y_i + \sum_{j,i} a_{ij} y_i x_j - \sum_j c_j x_j = \sum_i b_i y_i - \sum_j c_j x_j = 0.$$

Therefore, all our inequalities must be equalities and we obtain the desired result.  $\square$

## 2 Primal-dual algorithm

The main implication of Theorem 1 is that if  $x$  and  $y$  are feasible and satisfy the complementary slackness conditions, then they are optimal. This result leads us to the primal-dual algorithm in which we start with a feasible solution  $x$  and  $y$  and try to satisfy the conditions more and more.

For the sake of convenience, we consider the primal and dual programs as follows:

$$\min\{c^T x : Ax = b, x \geq 0\} \quad (P)$$

$$\max\{b^T y : A^T y \leq c\} \quad (D)$$

In this form, the complementary slackness conditions that we need to satisfy are reduced to:

$$\forall j \ (c_j - \sum_i a_{ij} y_i) x_j = 0. \quad (3)$$

The steps of the primal-dual algorithm are as follows:

1. Start with a feasible solution  $y$  for  $(D)$ . Obtaining such feasible solution  $y$  is easier than solving the linear program in many cases.

Let  $J = \{j : \sum_i a_{ij} y_i = c_j\}$ .

Now using 3, we need to obtain a solution  $x$  for  $(P)$  such that  $\forall j \notin J, x_j = 0$ . So the question is whether there is a feasible solution  $x$  with this property.

2. Formulate the restricted primal (RP) as follows:

$$\begin{aligned} & \min \sum_{i=1}^m X_i \\ \forall i \quad & \sum_{j \in J} a_{ij} x_j + X_i = b_i \\ & X_i, x_j \geq 0 \\ \forall j \notin J \quad & x_j = 0 \end{aligned}$$

In fact,  $(RP)$  formulates the problem of finding feasible solution  $x$  with the aforementioned property. Here variables  $X_i$ 's are artificial variables and if  $\min \sum_{i=1}^m X_i$  is equal to zero, then  $x_j$ 's are optimal solutions to  $(P)$ .

3. If  $Opt(RP) = 0$  then  $x$  and  $y$  are optimal. Otherwise  $Opt(RP) > 0$  and we write the dual of (RP), namely (DRP), for which we get solution  $\bar{y}$ .

$$\begin{aligned} & \max \sum_{i=1}^m b_i y_i \\ \forall j \in J \quad & \sum_i a_{ij} y_i \leq 0 \\ & y_i \leq 1 \end{aligned}$$

4. Improve the solution to (D) by setting  $y' = y + \epsilon \bar{y}$ . Here we determine  $\epsilon$  such that  $y'$  is feasible and  $\sum_i b_i y'_i > \sum_i b_i y_i$ . For feasibility, we must satisfy the condition  $\forall j \sum_i a_{ij} y'_i \leq c_j$ . For  $j \in J$ , we must have  $\sum_i a_{ij} y_i + \epsilon \sum_i a_{ij} \bar{y}_i \leq c_j$ . Since  $\forall j \in J \sum_i a_{ij} \bar{y}_i \leq 0$ ,  $\epsilon$  can be arbitrary positive for  $j \in J$ .

Thus by taking

$$\epsilon = \min_{\{j \notin J \text{ s.t. } \sum_i a_{ij} \bar{y}_i > 0\}} \frac{c_j - \sum_i a_{ij} y_i}{\sum_i a_{ij} \bar{y}_i}$$

we obtain our  $\epsilon > 0$  such that  $y'$  is feasible.

Also since  $Opt(DRP) = Opt(RP) > 0$  and  $\epsilon > 0$ ,

$$\sum_i b_i y'_i = \sum_i b_i y_i + \epsilon \sum_i b_i \bar{y}_i > \sum_i b_i y_i.$$

We note that in the above primal-dual algorithm, solving (DRP) is usually easier than solving (P) or (D). In fact, in this approach, programs (P) and (RP) are temporary programs and we want to solve (D). To this end, we first solve (DRP) and then use the solution to improve  $y$  iteratively.

## 2.1 Example

Consider the following formulation of the max-flow problem:

$$\begin{aligned}
& \max f \\
\sum_j x_{sj} - \sum_j x_{js} - f & \leq 0 \\
f - \sum_j x_{jt} + \sum_j x_{tj} & \leq 0 \\
\forall i \neq s, t \quad \sum_j x_{ij} - \sum_j x_{ji} & \leq 0 \\
x_{ij} & \leq u_{ij} \\
-x_{ij} & \leq 0
\end{aligned}$$

It is worth mentioning that in the original max-flow formulation, the first three sets of constraints are equalities. However in our new formulation by summing these three sets of inequalities, we get  $0 \leq 0$  and thus these weaker sets of inequalities imply the equalities.

Now, we consider the above formulation as  $(D)$ . One feasible solution to  $(D)$  can be obtained by taking  $x$  as a zero vector. Now if we go directly to  $(DRP)$  we have:

$$\begin{aligned}
& \max f \\
\sum_j x_{sj} - \sum_j x_{js} - f & \leq 0 \\
f - \sum_j x_{jt} + \sum_j x_{tj} & \leq 0 \\
\forall i \neq s, t \quad \sum_j x_{ij} - \sum_j x_{ji} & \leq 0 \\
x_{ij} & \leq 0 \quad \forall i, j \text{ where } x_{ij} = u_{ij} \text{ in } (D) \\
-x_{ij} & \leq 0 \quad \forall i, j \text{ where } x_{ij} = 0 \text{ in } (D) \\
x_{ij} & \leq 1 \\
f & \leq 1
\end{aligned}$$

We can observe that  $(DRP)$  has the following interpretation. Find a path from  $s$  to  $t$  (with a flow of value 1) that uses only the following arcs in the following ways: saturated arcs in the backward direction; arcs with zero flow in the forward direction; and other arcs in either direction. In other words, we need to find a path in the residual graph. This observation shows that the max-flow algorithm is in fact a primal-dual algorithm.

Finally, we note that primal-dual algorithms do not have polynomial running time guarantees.